

Providing User-Friendly Interfaces to SystemC/SystemC AMS Models through Simulink, Python and Browser for Enhanced Customer Experience

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Table of contents

- 1** Motivation
- 2 SIMULINK export
- 3 Python Interfaces
- 4 COS Panel

Motivation

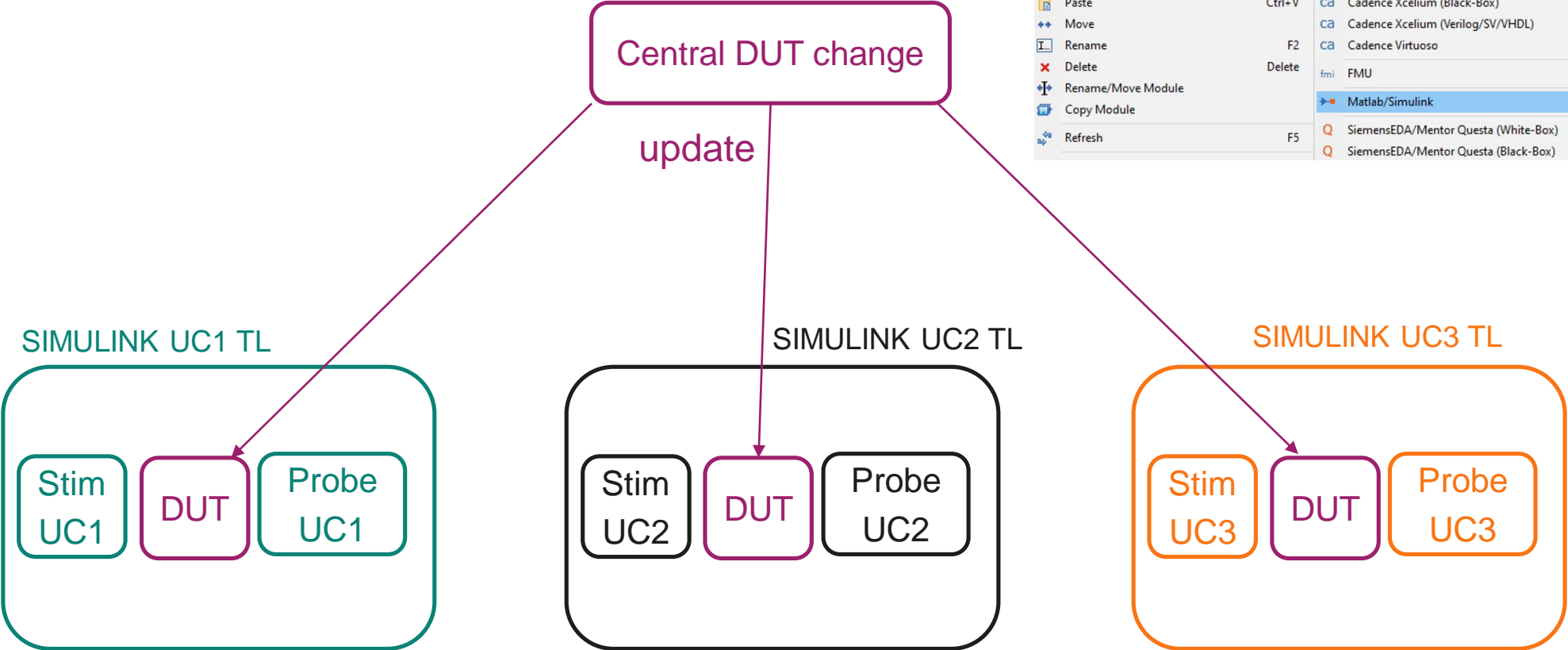
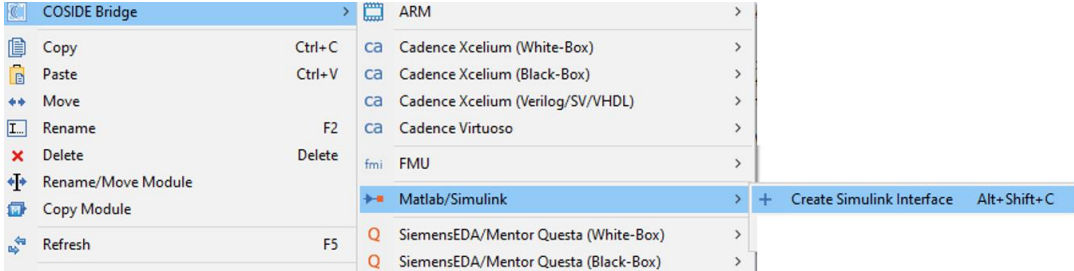
- Provide (customer) model in target environment
 - Allow early integration tests
 - Give customer performance indication already in early development state
 - Empower stakeholder understanding by providing „executable specification“
- Keep maintainable Black/grey box → secure IP and keep effort low
- Reach stakeholders not used to modelling/design environment
- Eliminate additional setup need

Table of contents

- 1 Motivation
- 2 **SIMULINK export**
- 3 Python Interfaces
- 4 COS Panel

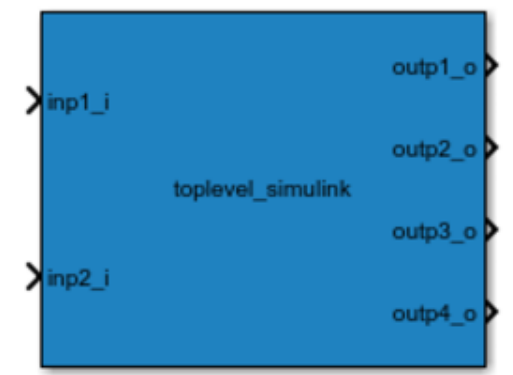
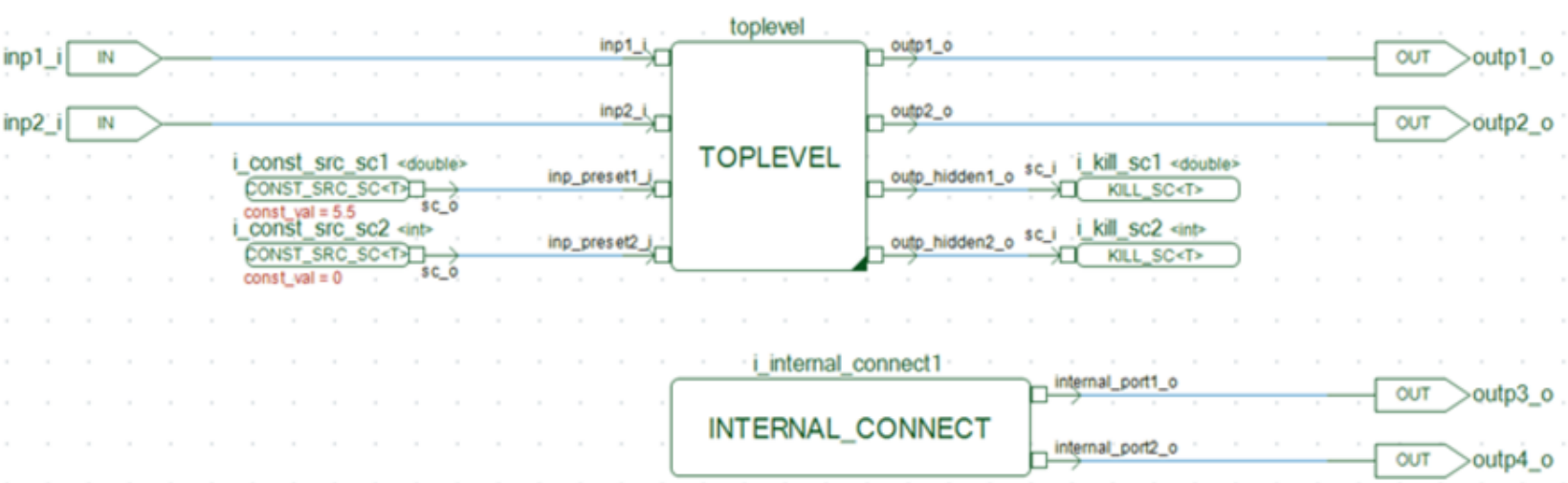
SIMULINK export

- Setup export TL and apply COSIDE® Coupling functionality on target xml
- Update/Generate export via make all (if the interface does not change, no maintenance necessary)
- Arbitrary number of customized TLs handleable



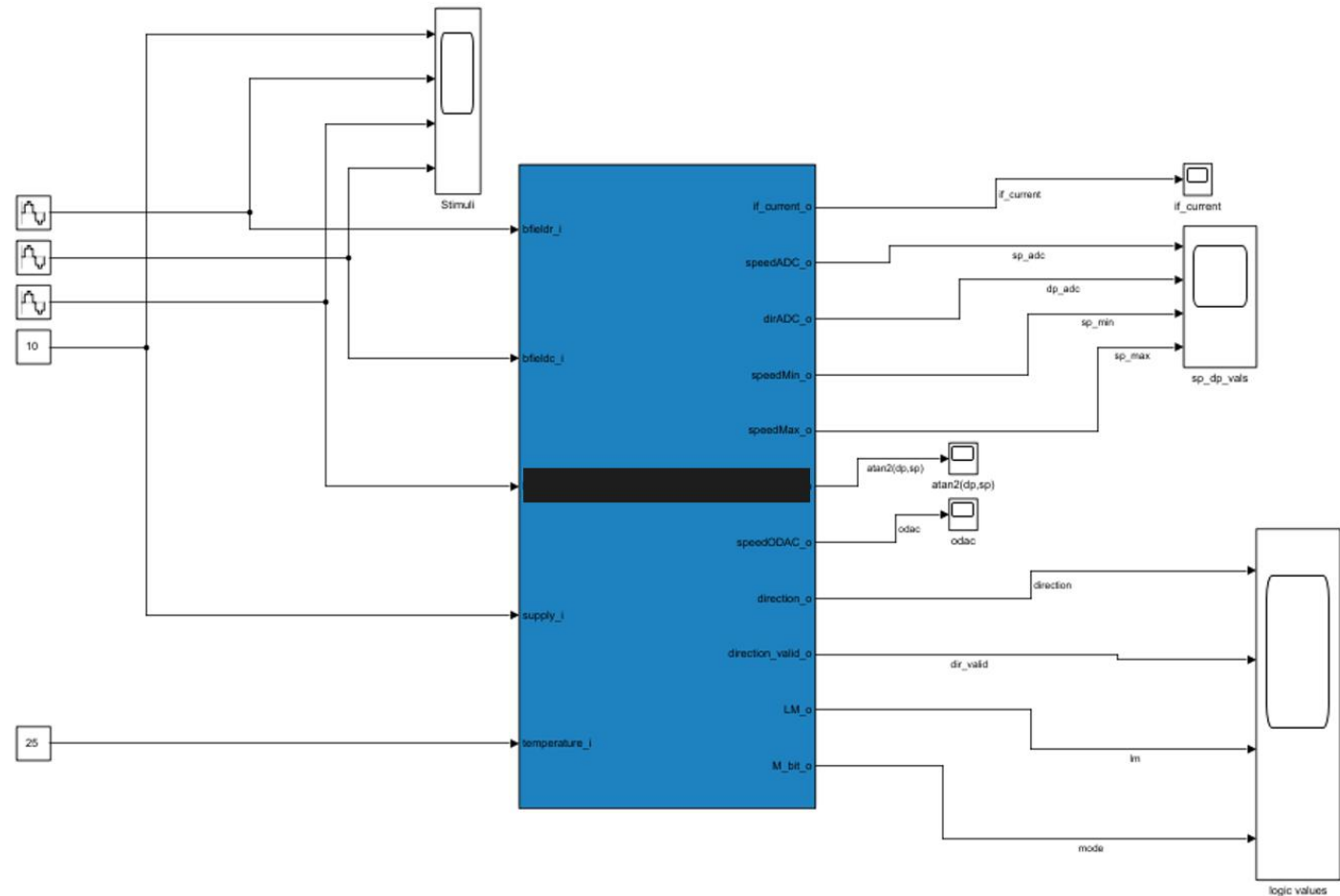
Maintain different IFs via schematics/instantiation in modules

- Provide useful interface adaptations to ease model handling & provide „spys“ on lower levels
 - preset inputs which the user shall not change/ do not need to care
 - Hide outputs which the user is not allowed to see/ do not need to care
 - Add internal signals to interface
- COSIDE® provides the functionality (cos_assign, hierarchical access, ...) to connect an outside block to signals within another block on arbitrary hierarchic levels - No need to adapt model interfaces ... Only modification of wrapper schematic necessary! (even global signal can be reached)

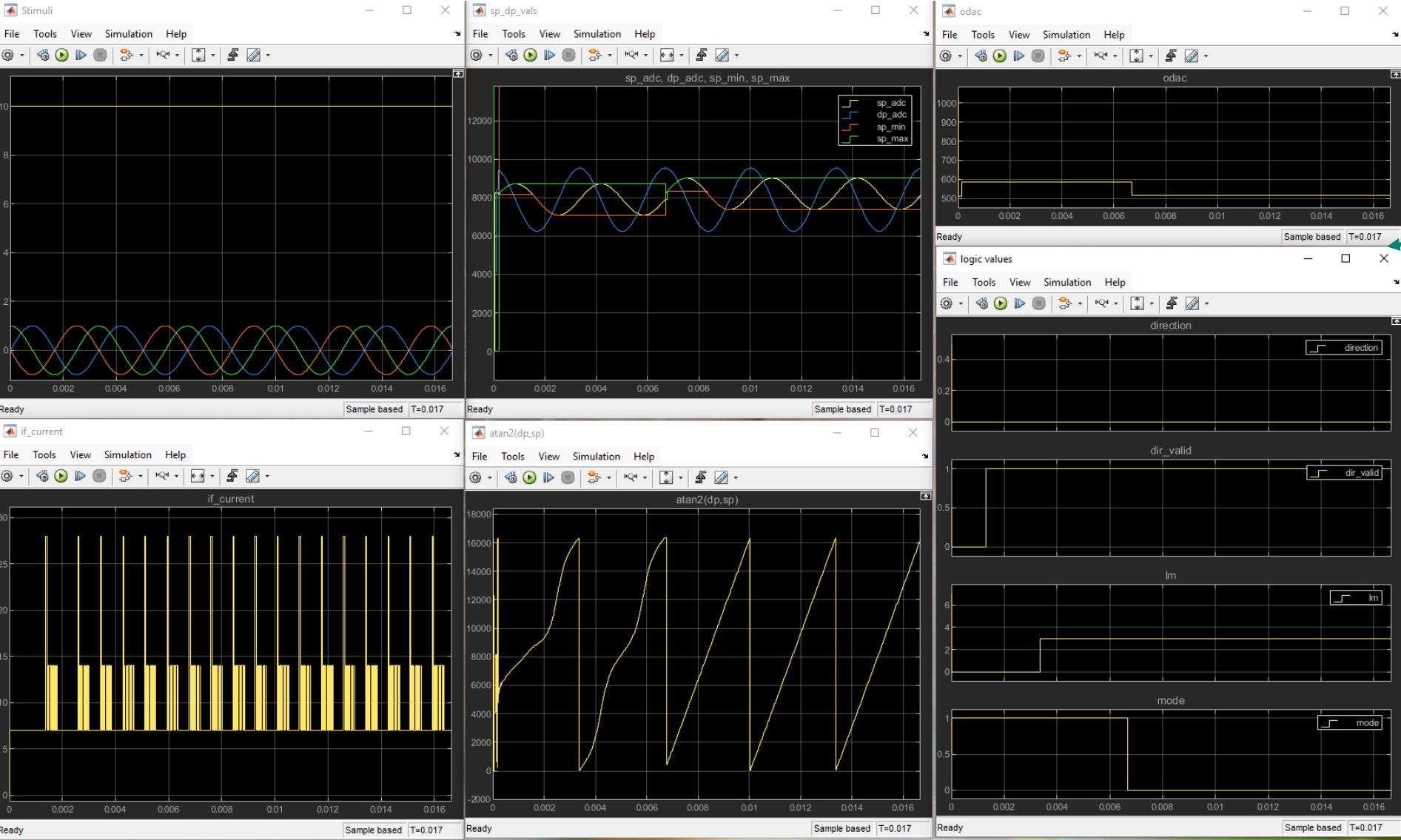


Deliver SIMULINK export to customer

- Easy drag and drop integration into simple TB
- Black Box attribute prevents later modification of provided IF
- Deliverable only requires mdl, mex (and opt. mingw) files
- Customer receives a meaningful executable OotB



Deliver SIMULINK export to customer example



These figures are just one click of the play button away

Parametrization supported by TL block

- TL parameter of the export entity will be present in the SIMULINK block GUI
 - Allows static configuration
 - Already present when module constructor is called

```

/// parameters
const struct params
{
    // 34_BEGIN_USER_CODE
    // you can add own code here.
    // END_USER_CODE_34
    std::string fuse_str; /** fuse file id */

    params()
    {
        // 35_BEGIN_USER_CODE
        // you can add own code here.
        // END_USER_CODE_35
        fuse_str = "";
    }
} p;

```

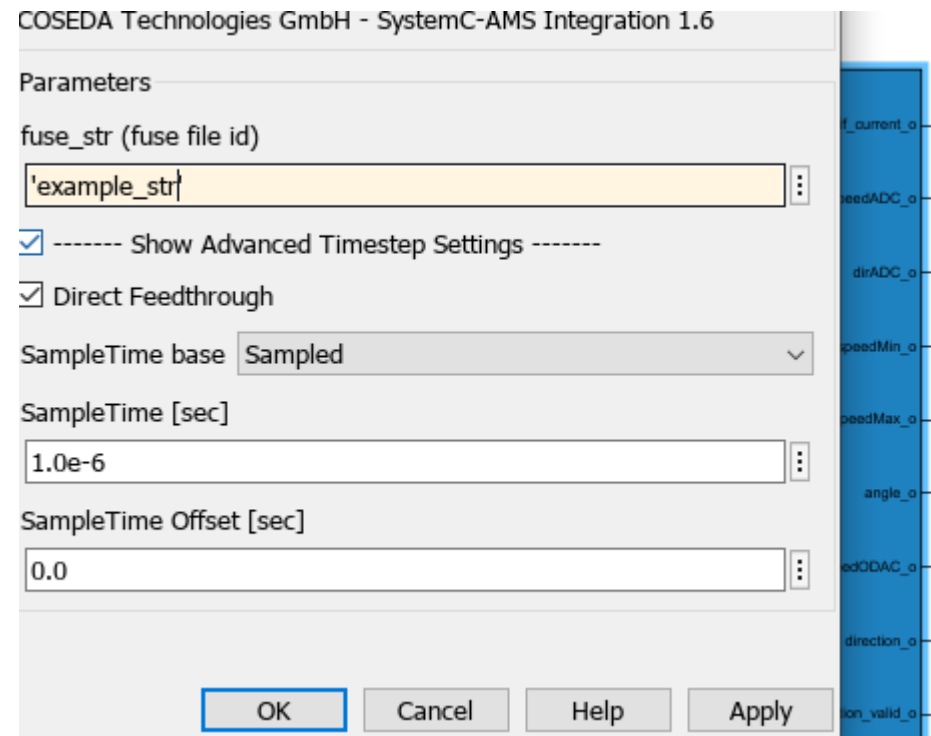
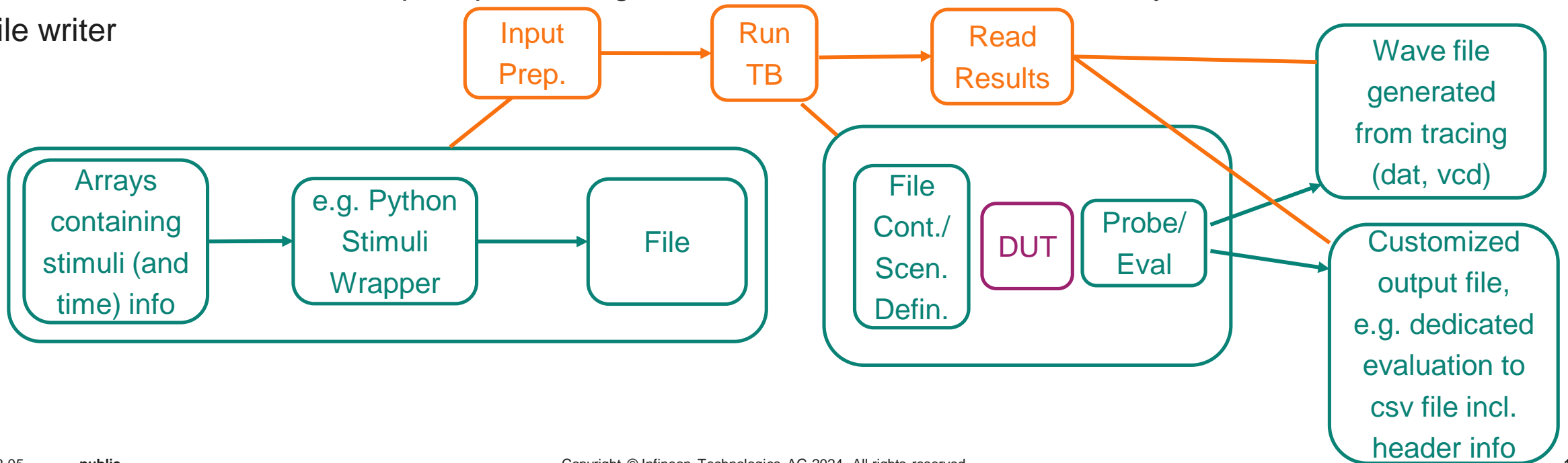


Table of contents

- 1 Motivation
- 2 SIMULINK export
- 3 Python Interfaces**
- 4 COS Panel

Connect to Python (or any other environment able to run executables)

- SystemC(-AMS) code compiled to binary is by its own nature a standalone Black Box export
- Straight forward ways to incorporate complex stimuli
 - Provide mapping from native description in target environment to generate a file structure, which is read in SystemC domain OR
 - Predefine stimuli by setting up scenarios by abstract definition or file structure and only allow selection via command line parameter / param reader
- Visualization and automated post-processing of behavior / more abstract results by wave files or customized file writer



Connect to Python (the interactive way)

- COSIDE® provides functionality to provide sim control to Python
- This includes e.g. Reading from and writing to signals as well as running the model for an arbitrary time
- Provided sequences can be a function of read back results
- Tracing can be adapted to the scenario
- Overall more freedom: Less effort to adapt IF, ...
- **Attention: IP protection might get violated**

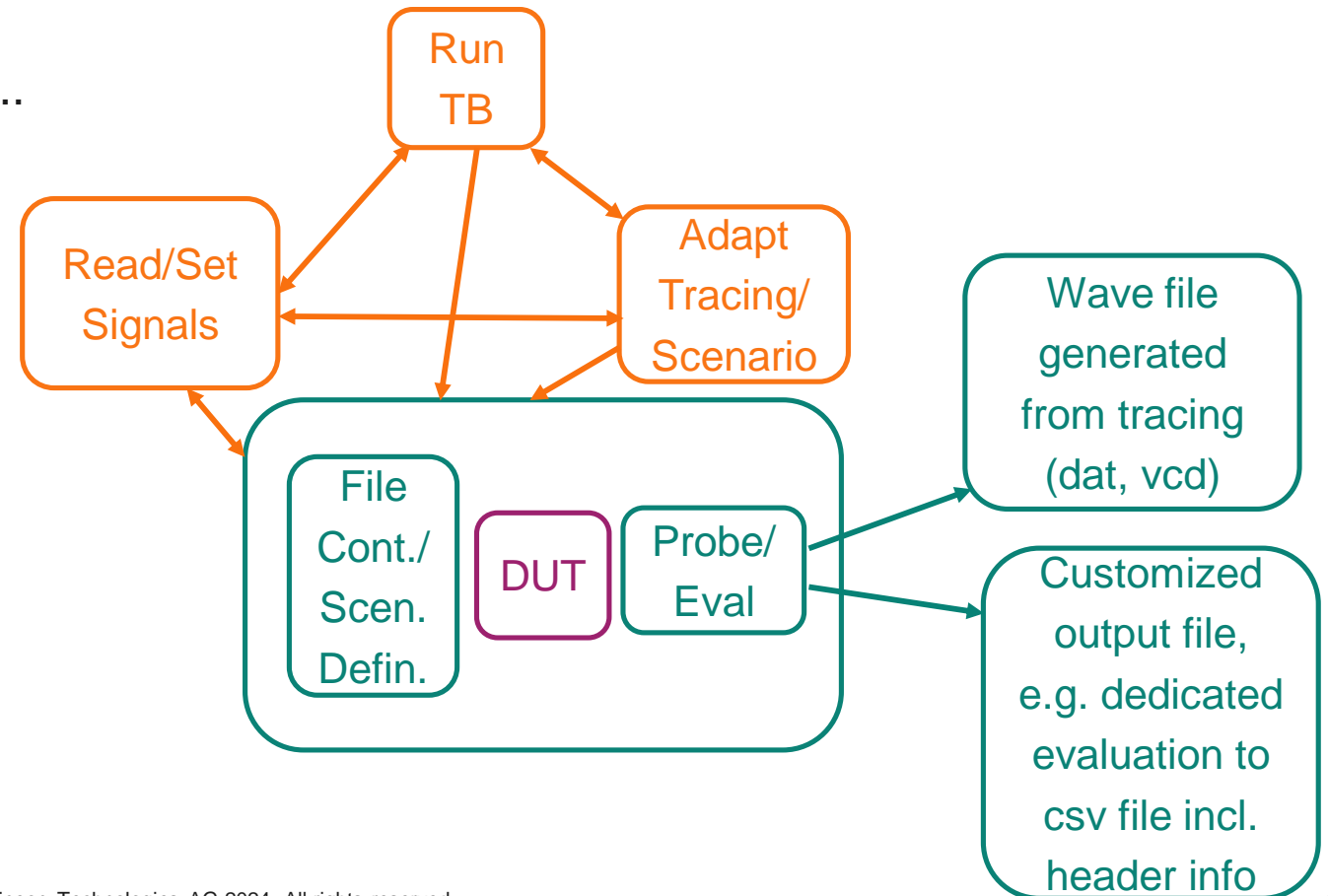


Table of contents

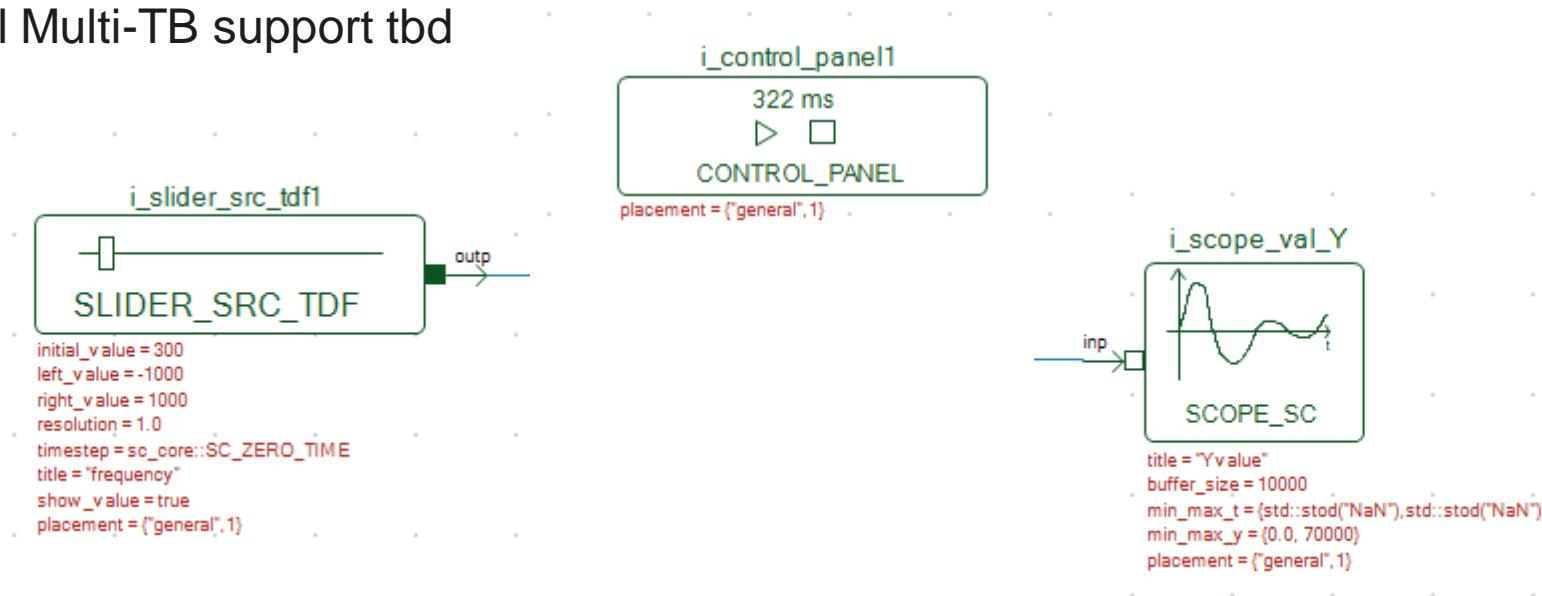
- 1 Motivation
- 2 SIMULINK export
- 3 Python Interfaces
- 4 **COS Panel**

SystemC(-AMS) GUI w/o Setup? → use your browser

- Insert special COS Panel modules to be used as IF
- Run local server (=run executable)
- Full control on I/O kept (and therefore IP can be protected)
- Based on Apache eCharts → Huge Visualization potential
- Customize the GUI by providing own HTML/CSS
 - Integrate your documentation/discalimer into the executable
 - Stick to corporate design
- Parallel Multi-TB support tbd

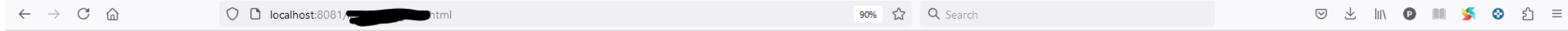
Link FE/BE by linking via string comparison

```
<div class="cos-grid-item">
  <h3>Displaying the simulation results...</h3>
  <div id="cos-panel:*.i_scope_val_*" style="width: 100%;"></div>
</div>
```



Info: cos_panel_controller:
Open: <http://localhost:8081>
in web browser

COS Panel FE example





Welcome to the Angle Sensor Web-GUI




Please use this panel to control the simulation in time domain.

Please click the play button to start the simulation...


 

Current simulation time: 21.7324 ms

Frequency slider:

 -1000.000000

Amplitude mismatch slider:

 1.250000

Infineon documentation link:

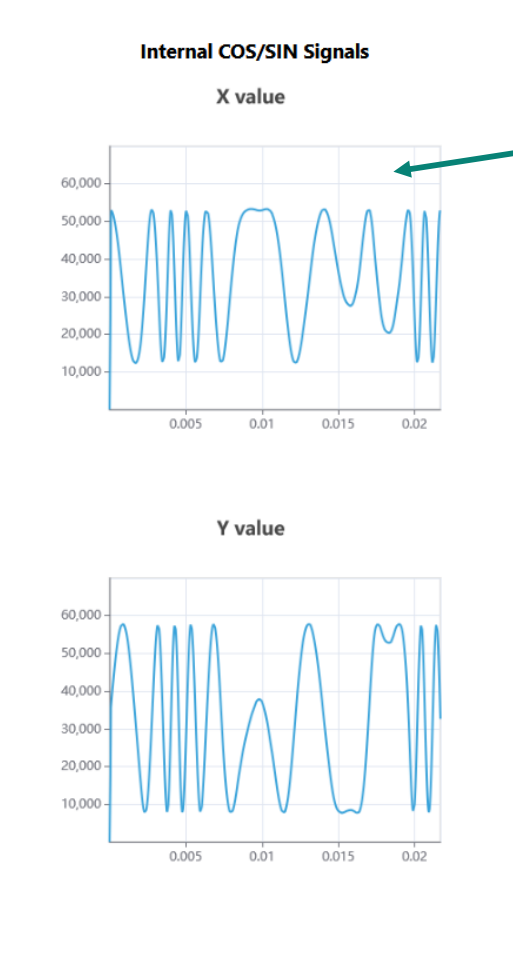
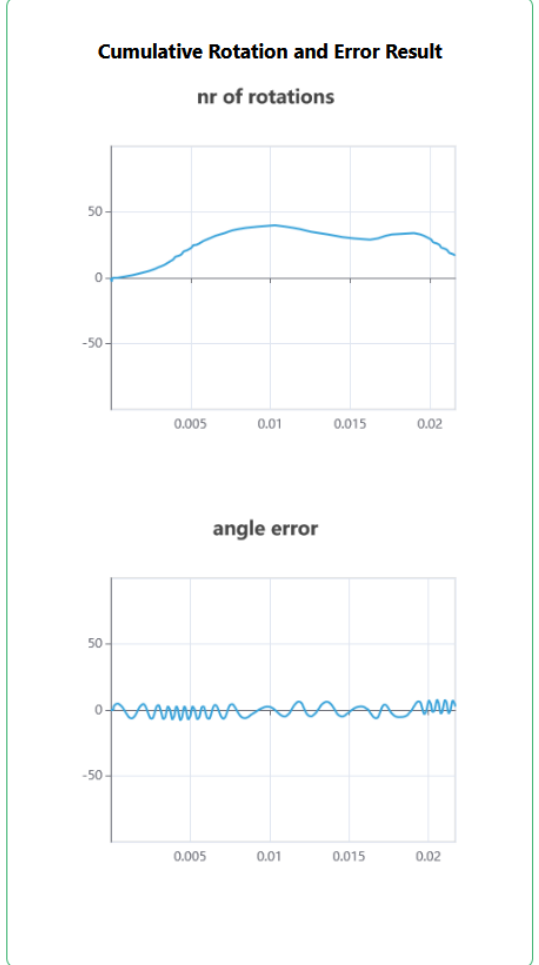
[User Manual Customer Model](#)

Disclaimer:

The present model targets to provide the executable behavior of a typical sample. Process variation is not covered.

Short documentation:

The frequency slider interactively sets the current frequency. Positive values refer to driving FWD, while negative frequencies refer to driving BWD. The amplitude mismatch defines the ratio between the amplitudes seen in X and Y.



Output elements are interactive as well, e.g. cursor, zoom, ..

Debug console shows e.g. non-instantiated as well as available cos panel elements

[open debug console](#)

Questions & answers



